

*Faustmann rotation and population dynamics in the presence  
of a risk of destructive events*

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# *Introduction*

- Management of natural resources : what is the optimal duration of cycle production ?
- Optimal production planning
- Optimal rotation : best sequence of harvesting

# *Introduction*

- Management of natural resources : what is the optimal duration of cycle production ?
- Optimal production planning
- Optimal rotation : best sequence of harvesting
- Presence of the Risk of a destructive event : Martell, Routledge (1980), Reed (1984 ...)

Faustmann rotation and Price uncertainty : Guttormsen (2001)

# *Faustmann Rotation*

- Faustmann solution solves Rotation problems
- A new rotation started at the same time as the previous one ends.
- Impact of rotation to harvesting ?
- Faustmann solution based on dynamic models

$$\max_{h(\cdot), T} J_0$$

# Population Dynamics

Model of a representative individual :

$$\text{Number } n(.) : \quad \frac{dn(t)}{dt} = -(m(t) + h(t))n(t)$$

$$\text{Status } s(.) : \quad \frac{ds(t)}{dt} = G(s(t), n(t))$$

$m$  : natural mortality

$h$  : harvesting rate,  $h(t) \leq \bar{h}$

Optimization problem (fixed term  $T$ ) :

$$\begin{aligned} \max_{h(.)} G_0 &= [H(n(.), s(.), h(.), T) + V_0(n(T), s(T))]e^{-\delta T} \\ &= V(T)e^{-\delta T} \end{aligned}$$

# Faustmann Rotation

Without risk :

$$J_0 = (J_0 + V(T) - c_1)e^{-\delta T}$$

Faustmann problem :

$$\max_T J_0 = \frac{V(T) - c_1}{e^{\delta T} - 1}$$

$$\max_{h(\cdot), T} \frac{H(n(\cdot), s(\cdot), h(\cdot), T) + V_0(n(T), s(T)) - c_1}{e^{\delta T} - 1}$$

## In presence of risk

Epidemics occur in a Poisson process at rate  $\lambda$  (average rate per unit time)

Proportion salvageable  $x_t$  with  $\alpha(t) = E(x_t)$

Three possibilities :

- For each event, stop and start a new cycle  
 $0 \rightarrow M(0, t_1) \rightarrow t_1$  ( $t_1 \leq T$ )
- For each event, continue  
 $0 \rightarrow M(0, t_1) \rightarrow t_1 \rightarrow M(t_1, t_2) \rightarrow t_2 \rightarrow \dots \rightarrow T$
- Criteria  $\left\{ \begin{array}{l} \text{stop and start a new cycle} \\ \text{continue} \end{array} \right.$

## In presence of risk : Case 1

$$J_0 = \int_0^T (J_0 + H(n(\cdot), s(\cdot), h(\cdot), t) + \alpha(t)V_0(n(t), s(t)) - c_2)e^{-\delta t} dF(t) \\ + (J_0 + V_0(n(T), s(T)) - c_1)e^{-\delta T}(1 - F(T))$$

$$\max_{h(\cdot), T} \frac{\delta + \lambda}{\delta} \left[ \int_0^T [H(n(\cdot), s(\cdot), h(\cdot), t) + \alpha(t)V_0(n(t), s(t))] \lambda e^{(\delta + \lambda)(T - t)} dt \right. \\ \left. + V_0(n(T), s(T)) - c_1 \right] / (e^{(\delta + \lambda)T} - 1) - \frac{\lambda}{\delta} c_2$$



## Optimal control

Using Pontryagin Maximum Principle :

$$\theta(t) = R'(t) - (\lambda(1 - \alpha(t)) + \delta + m(t))R(t) - c_n\lambda(1 - \alpha(t))$$

$$\Theta(t) = \int_t^T e^{(\lambda+\delta)(T_*-u)-\bar{h}(u-t)}\theta(u)du, \quad R(t) = p(s(t))$$

### Proposition

Assuming  $\theta'(t) < 0$ , let the optimal final term  $T_*$ , then :

- if  $\theta(T_*) \geq 0$ ,  $h_* \equiv 0$

- if  $\theta(T_*) < 0$ , it exists  $0 \leq t_* < T_*$  such that :  $h_*(t) = 0$ ,  $t < t_*$   
and  $h_*(t) = \bar{h}$ ,  $t > t_*$ .

Moreover, if  $\Theta(0) > 0$ ,  $t_*$  is given by :

$$\Theta(t_*) = \int_{t_*}^T e^{(\lambda+\delta)(T_*-u)-\bar{h}(u-t_*)}\theta(u)du = 0$$

else  $t_* = 0$ .

## *First conclusion*

- $m(t)$  replaced by  $m(t) + \lambda(1 - \alpha(t))$
- $\theta(t) - \theta_0(t) = -\lambda(1 - \alpha(t))(R(t) + c_n) < 0$
- Harvesting increases with risk in optimal management for a fixed final term  $T$

And for respective optimal final term  $T$  ?

## Simulation 1

$$\lambda = 0.01, \delta = 0.03, \alpha = 0.5, \bar{h} = 0.05, R(t) = t, c_1 = 11.5$$

Without risk :

$$h = 0 \Rightarrow T_* = 32., J_0 = 12.72n_0$$

With the presence of a risk :

$$h(t) = 0 \Rightarrow T_* = 30., J_0 = 4.98n_0$$

$$h(t) > 0, 18.5 \leq t \leq 37. \Rightarrow T_* = 37., J_0 = 5.12n_0$$

Higher final term  $T$ , the higher the probability of achieving the cycle low

## Simulation 2

$$\lambda = 0.02, \delta = 0.03, \alpha = 0.5, \bar{h} = 0.05, R'(t) = 0.9 + \frac{0.1n_0}{n(t)}, c_1 = 11.5$$

Without risk :

$$h = 0 \quad \Rightarrow T_* = 32.0, J_0 = 12.71n_0$$

$$h(t) > 0, 27.5 \leq t \leq 32.5 \quad \Rightarrow T_* = 32.5, J_0 = 12.72n_0$$

With the presence of a risk :

$$h = 0 \quad \Rightarrow T_* = 30.0, J_0 = 4.98n_0$$

$$h(t) > 0, 27.5 \leq t \leq 31.5 \quad \Rightarrow T_* = 31.5, J_0 = 5.00n_0$$

$$h(t) > 0, 15. \leq t \leq 40.5 \quad \Rightarrow T_* = 40.5, J_0 = 5.28n_0$$

## In presence of risk : case 2

Same hypothesis. In case of event, the cycle continues.

$$\max_{h(\cdot), T} \frac{H(\tilde{n}(\cdot), s(\cdot), h(\cdot), T) + V_0(\tilde{n}(T), s(T)) - c_1}{e^{\delta T} - 1}$$

$$\frac{d\tilde{n}(t)}{dt} = -(m(t) + \lambda(1 - \alpha(t)) + h(t))\tilde{n}(t)$$

where :  $\tilde{n}(t) = E_x(n(t))$

# *Conclusion*

- Harvesting increases with risk
- Larger harvesting induces larger final term
- Final term can be larger with risk
- Density dependence
- Criterion of decision
- Influence of model complexity

# THANK YOU FOR YOUR ATTENTION

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