

Dynamic waves and the harvest of multiple rotations

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Research Question

When should distant or less accessible but older stands be harvested rather than closer or more accessible but younger stands?

Background/Context

European settlement of North America

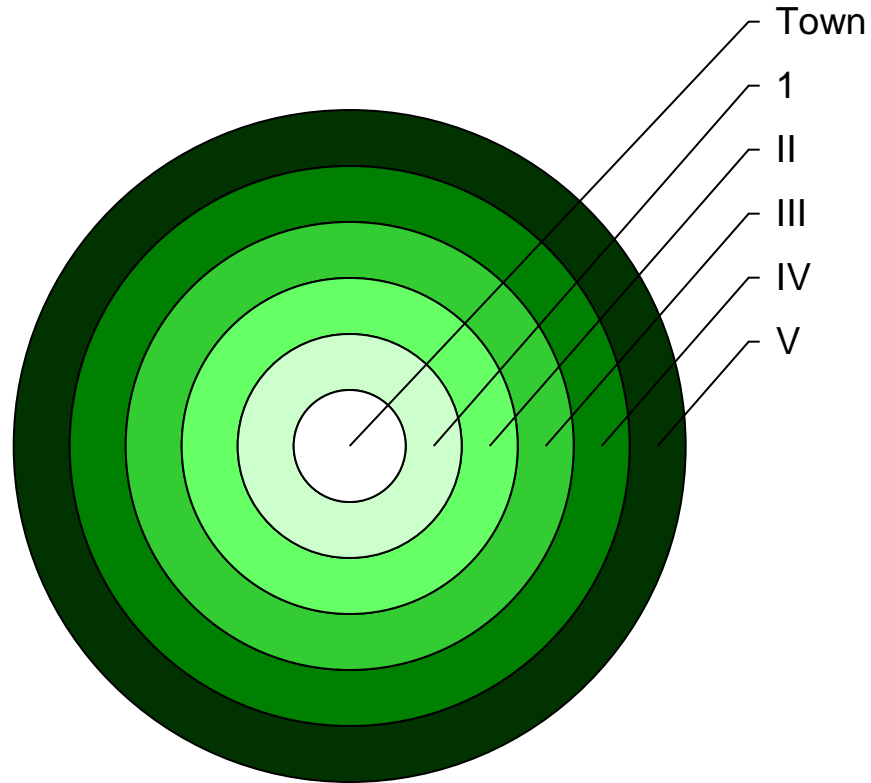
Two geographical patterns

- Over time “old growth” forests harvested by region
- More accessible/closer stands harvested first

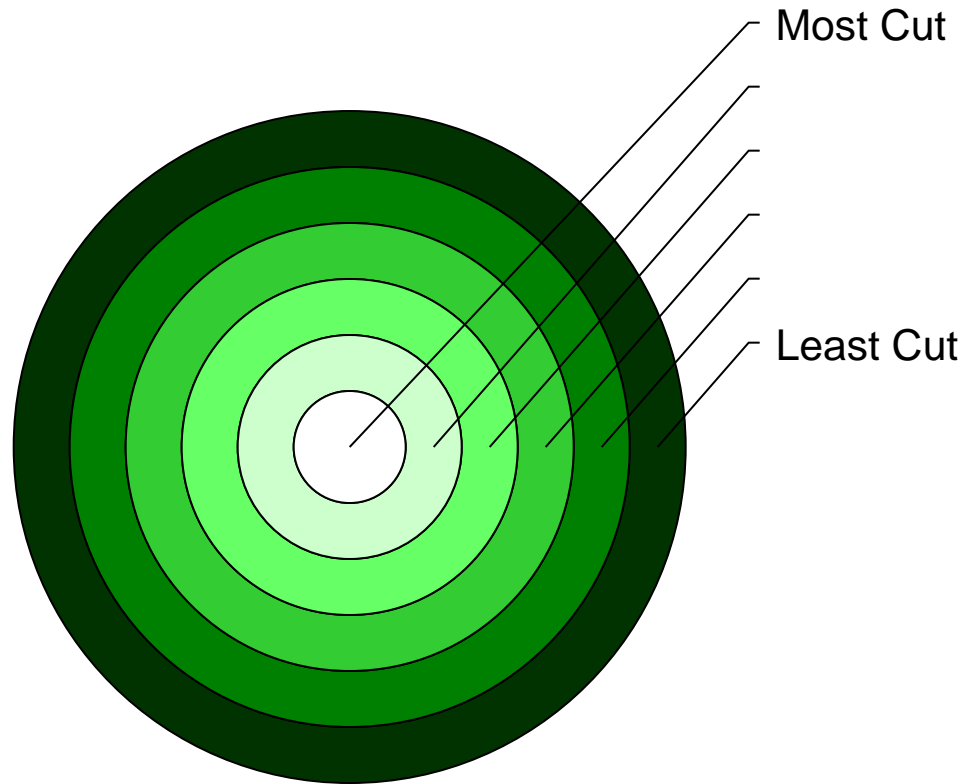
Caveats

- Déjà vu
- Incomplete progress
- Lying: no numerical simulation
- Shading the truth:
characterization of a derivation rather
than derivation of results

von-Thunen Rings



Rotations



Model Characterization

- Each rotation can be modeled as a depletion problem with stands/trees that grow
- At any time it may be optimal to harvest from more than one rotation
- Let a regime be the area harvest of some set of one or more rotations
- Regime switching problem

Progress since 1999

- Some new results on multiple-phase optimal control problems: Doole 2008, Doole 2009 (switching conditions)
(Older results: Amit 1986; Makris 2001)
- Development of notation (harvest ages for all hectares & rotations)

Multiple-phase switching problem

- Implies that the transversality conditions for switching between harvesting regime j and harvesting regime $j+1$ are derivable
- Which implies that the transversality conditions for switching between harvesting rotation i and harvest rotation $i+1$ rotations are derivable
- Each rotation can be set up as a standard DP (or optimal control problem)

Harvest order & notational simplification

From Hartwick 1977 it is easy to show:

- The order of hectares harvested is invariant over rotations
- The harvest of lower numbered rotations will start before the harvest of higher numbered rotations

Harvest order, computational ease & notational simplification

- Determines harvest order within a rotation
- Limits the number of comparisons required at each time (number of rotations currently being harvested plus one)
- Allows harvesting regimes to be defined

Objective Functional for each rotation

For every a and t ,

$$V(X(t)) = \max_{H(a,t)} U\left(\sum_{a=0}^{a_{\max}} (P(a,t)Y(a) - C)H(a,t)\right) + BV(X(t+1))$$

where

a is stumpage age,

a_{\max} is maximum harvest age,

B is the discount factor, i.e., $B = (1+r)^{-1}$,

C is the fixed regeneration cost,

$H(a,t)$ is hectares of age a stumpage harvested at time t ,

$P(a,t)$ is the per meter stumpage price for age a stumpage at time t ,

$X(t)$ is the vector of $X(a,t)$'s

$Y(a)$ is the volume for age a stumpage; $Y(\cdot)$ is the volume function,

$U(\cdot)$ is the per period utility function, and

$V(\cdot)$ is the NPV from timber production given an initial vector of stock sizes $X(t)$.

The objective is to maximize the sum of this period's utility and the discounted state of next period's stock.

State Equations

For every t and $a = 2$ to a_{\max} : $X(a+1,t+1) = X(a,t) - H(a,t)$

For every t and $a = 1$: $X(1,t+1) = X_1$

For ages 2 to a_{\max} , the number of hectares in age class $a+1$ at time $t+1$ is the number of hectares in age class a at time t minus the number of hectares harvested at time $t+1$

For age class 1, the number of hectares at time $t+1$ is the number of hectares harvested at time t

Constraints

For every a and t , $0 \leq H(a,t) \leq X(a,t)$;

For every age and every time, harvest is non-negative and less than or equal to the stock.

Multiple-phase solution

- Multiple-phase solution requires simultaneous determination of control variables and switching times
- Switching times are determined when setting the co-state variables of regime j and regime $j+1$ are equal

Conclusion

- Multiple phase optimal control is applicable for a range of forest economics questions, specifically, when stands vary in age and spatial accessibility
- For some forest economics questions numerical simulation will be difficult because of the size of the decision space